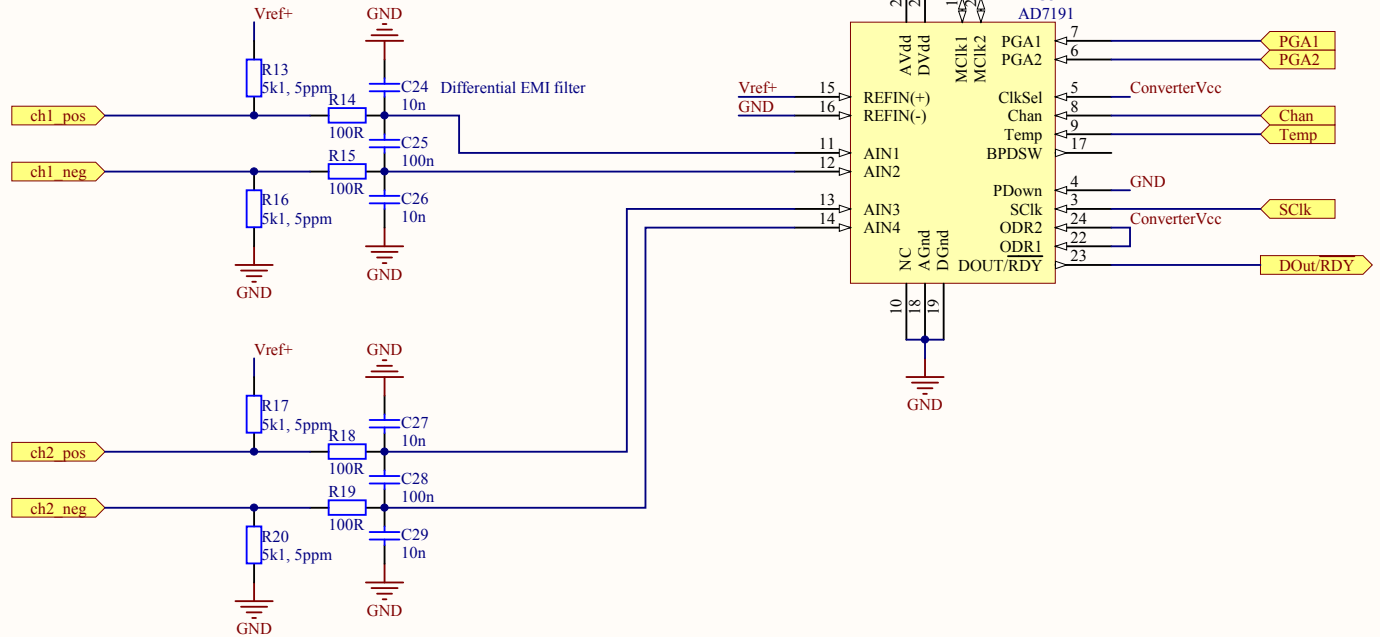
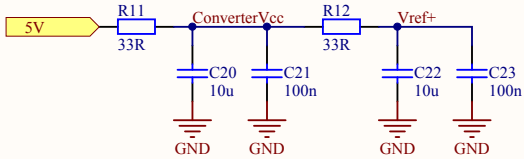


**Power supply filtering:**

33R + 10uF -> 500 Hz pole

Converter draws 5 mA  
Reference arm draws 0.25 mA



**Performance with a typical thermistor (R25 = 10K) :**

Resolution at the gain=1, rate=10 Hz, RMS noise floor of 500 nV:  
-50 degC to +120 degC : < 0.1 mK  
0 degC to 35 degC : < 10 uK

Error in measured T from tempCo (5ppm) of bridge resistors:  
0.07 mK / K @ -50 degC (thermistor)  
0.1 mK / K @ 20 degC (thermistor)  
0.2 mK / K @ 120 degC (thermistor)

Error from converter offset drift (150 nV / K @ gain=1):  
< 35 uK / K (-50 degC to +120 degC thermistor)  
2 uK / K @ 20 degC (thermistor)

Error from converter gain drift (1ppm / K):  
1 mK / K @ -50 degC (very fast drop off to this value below -20 degC)  
< 0.1 mK / K @ Troom > 0 degC

Total error from ambient drifts @ thermistor = 20 degC: 0.2 mK / K  
(note that a large part of this could be removed by applying a correction calculated from the internal temperature sensor of the AD7191)

Gain drift over time: 10 ppm / 1000 hours gives < 1 mK @ Troom > 0 degC over 1000 hours

**Errors from power supply noise and drift:**

Supply rejection:  
90 dB -> 30 uV / V  
Thus 10 mV noise gives 300 nV shift -> 4 uK (nothing)

Common mode input rejection (rate=10Hz):  
120 dB -> 1 uV / V  
So 100 mV of 50 Hz / 60 Hz noise -> 1 uK

Title		
<b>Digital temperature controller</b>		
Size	Number	Revision
A4		1
Date:	09/08/2013	Sheet2 of 3
File:	Z:\Users\...tempSensor.SchDoc	Drawn By: CJB